Processes of fragmentation and coagulation – Smoluchowski's equations and beyond

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Marian Smoluchowski, 28 May 1872 – 5 September 1917

XXXVI. DREI VORTRÄGE ÜBER DIFFLISION, BROWN-SCHE MOLEKULABERFEDUNG UND KOAGULATION VON KOLLOIDTEILCHEN.

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Versuch einer mathematischen Theorie der Koagulationskinetik kolloider Lösungen.

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I. Einleitung.

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Fragmentation-coagulation processes

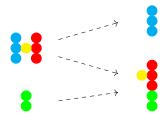


Figure: Pure fragmentation and coagulation

Coagulation and fragmentation belong to the most fundamental processes occurring in animate and inanimate matter. The range of applications includes:

- Chemical engineering: polymerization/depolimerization processes, with possible mass loss through dissolution, chemical reactions, oxidation etc, or mass growth due to the deposition of material on the clusters.
- Biology: Blood cells' coagulation and splitting, animal grouping, phytoplankton at the level of aggregates, flocculation.
- Planetology: merging of planetesimals.
- Aerosol research: coagulation of smoke, smog and dust particles, droplets in clouds.

Thus, together with the Boltzmann equation that describes collision phenomena in rarefied gases, the Navier-Stokes and Euler equations modelling the flow of viscous fuids, the coagulation-fragmentation equation, in its original form going back to Smoluchowski, describing rearrangements of particles, is considered to be one of the most fundamental equations of the classical description of matter.

We shall refer to the fundamental building blocks of the aggregates as monomers and a cluster of n monomers will be called an n-mer. The Smoluchowski population balance equations, describing the time-evolution of the number density of n-mers of size $n \geq 2$, is given by

$$\frac{df_n}{dt}(t) = -a_n f_n(t) + \sum_{j=n+1}^{\infty} a_j b_{n,j} f_j(t)
+ \frac{1}{2} \sum_{j=1}^{n-1} k_{n-j,j} f_{n-j}(t) f_j(t) - \sum_{j=1}^{\infty} k_{n,j} f_n(t) f_j(t), \quad (1)$$

where

- $f_n(t)$ is the number density of n-mers at time $t \ge 0$;
- a_n is the net rate of break-up of an n-mer;
- $b_{n,i}$ is the daughter distribution function that gives the average number of *n*-mers produced upon the break-up of a *j*-mer;
- $k_{n.i} = k_{i.n}$ represents the coagulation rate of an n-mer with a *i*-mer.

Since monomers do not fragment and loss of monomers can only arise due to coagulation, for n = 1 we have

$$\frac{d}{dt}f_1(t) = \sum_{j=2}^{\infty} a_j b_{1,j} f_j(t) - \sum_{j=1}^{\infty} k_{1,j} f_1(t) f_j(t). \tag{2}$$

Continuous fragmentation-coagulation models

In many applications, such as aerosols or polymers, it makes sense to allow the clusters to be of any size. Then the size of building blocks must be infinitesimal and hence we consider a continuous size variable $x \in \mathbb{R}_+$ as the only variable required to differentiate between the reacting particles.

Then,

$$\partial_t f(t,x) = \mathcal{F} f(t,x) + \mathcal{C} f(t,x) , \qquad (t,x) \in (0,\infty)^2 , \quad (3)$$

$$f(0,x) = \mathring{f}(x), \qquad x \in (0,\infty), \qquad (4)$$

where

$$\mathcal{F}f(t,x) = -a(x)f(t,x) + \int_{x}^{\infty} a(y)b(x,y)f(t,y) \,\mathrm{d}y, \qquad (5)$$

and

$$Cf(t,x) = \frac{1}{2} \int_0^x k(x-y,y)f(t,x-y)f(t,y) dy$$
$$-f(t,x) \int_0^\infty k(x,y)f(t,y) dy$$
(6)

Here f is the density of particles of mass x, a is the fragmentation rate and b describes the distribution of particle masses x spawned by the fragmentation of a particle of mass y. Further

$$M(t) = \int_{0}^{\infty} x f(x, t) dx$$
 (7)

is the total mass at time t. Local conservation principle requires

$$\int_{0}^{y} xb(x,y)dx = y,$$
(8)

with the expected number of particles produced by a particle of mass y is given by

$$n_0(y) = \int\limits_0^y b(x,y)dx.$$

Fragmentation-coagulation equation with vital dynamics.

Organisms' grouping

- active, resulting from conscious actions of individuals (herds, swarms, fish schools),
- passive, resulting from physical or chemical properties of the organisms and the dynamics of the surrounding medium (bacteria, phytoplankton aggregates).

Why do animals form groups?

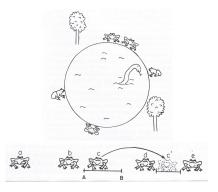


Figure: Frogs' grouping to reduce danger zone, W.D. Hamilton, Geometry of Selfish Herd, JTB, 1971

Fish schools

Niwa (2003, 2004) observed that fish school-size distribution $(f_i)_{i\geq 1}$ is well described by

$$f_i \sim \frac{1}{i_{av}} \Phi\left(\frac{i}{i_{av}}\right),$$

where

$$i_{av} = \sum_{i=1}^{\infty} i \frac{if_i}{\sum_{i=1}^{\infty} if_i}$$

is the average size the group an individual belongs to and

$$\Phi(x) = \frac{1}{x} e^{-x+0.5xe^{-x}} \approx \frac{1}{x} e^{-x}.$$

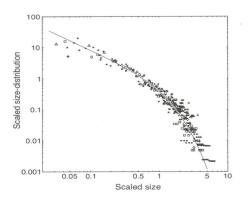


Figure: Empirical school size distribution of six types of pelagic fish (Niwa, 2003)

For a Smoluchowski type model, Degond derives

$$\Phi_{\star}(x) = 2(6x)^{-2/3} \sum_{n=0}^{\infty} \frac{(-1)^n}{\Gamma\left(\frac{4}{3} - \frac{2}{3}n\right)} (6x)^{n/3}$$

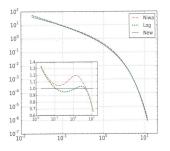
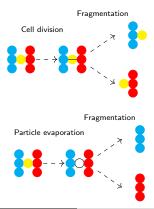


Figure: Plot of Φ for Niwa's, simplified Niwa's and Degond's distribution profiles. Inset: ratios Φ/Φ_* for all three cases. (Degond et al., 2017)

Fragmentation-coagulation with growth and decay.

In all discussed models the fragmentation and coagulation processes, which are just rearrangements of monomers, should be accompanied by growth (and death) terms — if a cell divides inside a cluster, it increases in size.



Then, in the continuous case, fragmentation can be supplemented by growth/decay, transport or diffusion processes. For instance,

$$\partial_{t}f(x,t) = \pm \partial_{x}[r(x)f(x,t)] - a(x)f(x,t)$$

$$+ \int_{x}^{\infty} a(y)b(x,y)f(y,t)dy$$

$$+ \frac{1}{2} \int_{0}^{x} k(x-y,y)f(t,x-y)f(t,y) dy$$

$$- f(t,x) \int_{0}^{\infty} k(x,y)f(t,y) dy$$
 (9)

where r(x) > 0 describes either decay of the substance (e.g. by chemical reaction or simply evaporation or dissolving) with "+" or growth by birth or multiplication, with "-" (evolution of phytoplankton aggregates.)

Why do we need functional analysis to deal with such models?

Fragmentation just rearranges the mass distribution and the total mass should be conserved by (8). However, consider a fragmentation equation describing binary fragmentation: with b(x,y)=2/y and a(x)=1/x it takes the form

$$\partial_t f(x,t) = -x^{-1} f(x,t) + 2 \int_{-x}^{\infty} y^{-2} f(y,t) dy,$$
 (10)

For mono-disperse initial condition $f(x,0) = \delta(x-l)$, l > 0, it has a solution

$$f_l(x,t) = e^{-t/l} \left(\delta(x-l) + \frac{2t}{l^2} - \frac{t^2}{l^2} \left(\frac{1}{l} - \frac{1}{x} \right) \right), \quad x \le l, \quad (11)$$

and $f_I(x,t) = 0$ for x > I. Hence the total mass of the ensemble is given by

$$M(t) = e^{-t/I} \left(I + t + \frac{t^2}{2I} \right), \tag{12}$$

and clearly decreases monotonically in time.

Solutions do not have the properties used for the derivation of the model

Multiple solutions.

On the other hand, taking a(x) = x, b(x, y) = 2/y yields

$$\partial_t f(x,t) = -xu(x,t) + 2\int\limits_{-\infty}^{\infty} f(y,t)dy. \tag{13}$$

Separating variables we get

$$f_1(x,t) = \frac{e^t}{(1+x)^3},$$
 (14)

with initial condition $f_1(x,0) = (1+x)^{-3}$ (of finite mass).

However,

$$f_2(x,t) = e^{-xt} \left(\frac{1}{(1+x)^3} + \int_{x}^{\infty} \frac{1}{(1+x)^3} [2t + t^2(y-x)] dy \right),$$

is also a solution to (13) satisfying the same initial condition.

Another example of nonuniqueness for this equation is offered by

$$f(t,x) = t^2 e^{-xt}. (15)$$

Routine calculations show that this function is a nontrivial solution to (13) emanating from zero so that (13) is not well-posed in the pointwise sense.

This shows that to ensure well-posedness of the problem we must carefully define what we mean by the solution.

Mathematical setting - state spaces.

Example 1

 $\alpha > 1$.

The natural space to analyse the continuous fragmentation - coagulation processes is

$$X_1 = L_1(\mathbb{R}_+, xdx) = \left\{ u; \ \|u\|_1 = \int_0^\infty |u(x)| x dx < +\infty \right\}$$

as for nonnegative u we have $||u||_1 = M(u)$, the mass of the ensemble with density u. Best results are obtained in spaces

$$X_{1,\alpha} = L_1(\mathbb{R}_+, (1+x^{\alpha})dx) = \left\{ u; \ \|u\|_{0,\alpha} = \int_0^{\infty} |u|(1+x^{\alpha})dx < +\infty \right\},$$

Ways of approaching the fragmentation-coagulation equations.

Difficulties in solving

$$\partial_t f(t,x) = \mathcal{F} f(t,x) + \mathcal{C} f(t,x) , \qquad (t,x) \in (0,\infty)^2 ,$$

$$f(0,x) = \mathring{f}(x) , \qquad x \in (0,\infty) , \qquad (16)$$

come from the fact that both the fragmentation rate a and the coagulation rate can be unbounded, for instance at $x = \infty$.

1. Truncation method. We construct solutions f_r to the problem with the coefficients a and k modified as follows

$$a_r(x) = \begin{cases} a(x) & \text{for } x \leq r \\ 0 & \text{for } x > r, \end{cases} \quad k_r(x,y) = \begin{cases} k(x,y) & \text{for } x + y \leq r \\ 0 & \text{for } x + y > r. \end{cases}$$

 $(f_r)_{r>0}$ is a weakly compact net whose accumulation point is a solution to a suitable weak formulation of (16).

Advantages: possibility to handle very general coagulation coefficients.

<u>Disadvantages:</u> weak solutions, additional work required to prove mass conservation, uniqueness, etc; fragmentation subordinated to coagulation.

2. Semigroup method. Considering (16) as a nonlinear perturbation of the linear dynamics generated by

$$\mathcal{F} = \mathcal{A} + \mathcal{B}$$
.

Advantages: classical unique mass-conserving solutions.

<u>Disadvantages:</u> The coagulation part subordinated to the fragmentation, typically bounded.

So, first, how to solve

$$\partial_t f = \mathcal{F} f = \mathcal{A} f + \mathcal{B} f$$
?

Between model and its analysis

Equations derived through a modelling process are formulated pointwise: all operations, such as differentiation and integration, are understood in the classical 'calculus' sense and the equation should be satisfied for all values of the independent variables:

$$\frac{\partial}{\partial t} f(t, x) = [\mathcal{K} f(t, \cdot)](x), \quad x \in \Omega$$

$$f(t, 0) = \mathring{f}, \tag{17}$$

where \mathcal{K} is a differential, integral, or functional expression. We aim to describe the evolution by a family of operators $(G(t))_{t\geq 0}$ in a state space X, parameterised by time, that map an initial state \mathring{f} of the system to all subsequent states in the evolution.

That is, solutions are represented as

$$f(t) = G(t)\mathring{f}. \tag{18}$$

From G we expect some form of continuity in t, the semigroup property $G(t+s)=G(t)G(s), t,s\geq 0$, and G(0)=Id. Then we try to write (17) as the Cauchy problem for an ordinary differential equation in X: for t>0

$$\partial_t f = Kf, \qquad f(0) = \mathring{f} \in X, \tag{19}$$

where K is certain realization of K in X. Problem (19) is well-posed if K is the generator of $(G(t))_{t\geq 0}$.

Semigroups - crash course

Let X be a Banach space, K be a linear operator in X with domain D(K).

Definition 2

A family $(G(t))_{t\geq 0}$ of bounded linear operators on X with G(0)=I, is called a C_0 -semigroup if

(i)
$$G(t+s) = G(t)G(s)$$
 for all $t, s \ge 0$;

(ii)
$$\lim_{t\to 0^+} G(t)f = f$$
 for any $f\in X$.

An operator K is called the generator of $(G(t))_{t\geq 0}$ if

$$Kf = \lim_{h \to 0^+} \frac{G(h)f - f}{h},\tag{20}$$

and D(K) is the set of all $f \in X$ for which this limit exists.

From (20) and (ii), for $\mathring{f} \in D(K)$ we have

$$\partial_t G(t)\mathring{f} = KG(t)\mathring{f}, \quad t > 0,$$

$$G(0)\mathring{f} = \mathring{f}, \tag{21}$$

so the function $f(t,\mathring{f}) = G(t)\mathring{f}$ is a classical solution to the Cauchy problem (19). If $\mathring{f} \in X \setminus D(K)$, the function $f(t,\mathring{f}) = G(t)\mathring{f}$ is continuous but, in general, not differentiable.

Thus, if we have a semigroup, we can identify the Cauchy problem of which it is a solution. We are, however, interested in finding the semigroup for a given equation. Let $\sigma(K)$ denote the spectrum of K and $\rho(K) = \mathbb{C} \setminus \sigma(K)$ be the resolvent set of K.

Theorem 3 (Hille-Yosida)

 $K \in \mathcal{G}(M,\omega)$ if and only if K is closed and densely defined and there exist $M>0, \omega \in \mathbb{R}$ such that $(\omega,\infty) \subset \rho(K)$ and for all $n\geq 1, \lambda>\omega$,

$$\|(R(\lambda,K))^n\| = \|((\lambda I - K)^{-1})^n\| \le \frac{M}{(\lambda - \omega)^n}.$$
 (22)

Analytic semigroups

If a densely defined K is sectorial, that is, if the estimate

$$||R(\lambda, K)|| \le \frac{C}{|\lambda|}.$$
 (23)

holds in some sector

$$S_{\frac{\pi}{2}+\delta} := \{\lambda \in \mathbb{C}; |\arg \lambda| < \frac{\pi}{2} + \delta\} \cup \{0\}, \quad \delta > 0, \tag{24}$$

then K is the generator of an analytic semigroup given by

$$G_{K}(t) = \frac{1}{2\pi i} \int_{\Gamma} e^{\lambda t} R(\lambda, K) d\lambda, \qquad (25)$$

where Γ is an unbounded smooth curve in $S_{\frac{\pi}{2}+\delta}$.

Benefits of analyticity

If K is sectorial, then

- $t \to G_K(t)\mathring{f}$ solves the Cauchy problem (21) for arbitrary $\mathring{f} \in X$;
- it is possible to define fractional powers $(-K)^{\alpha}$, $0 < \alpha < 1$, with domains satisfying

$$D(K) \subset D((-K)^{\alpha}) \subset X$$
;

• for every t > 0 and $0 \le \alpha \le 1$, we have

$$||t^{-\alpha}(-K)^{-\alpha}G_K(t)|| \le M_{\alpha}$$
 (26)

for some constant M_{α} .

For example, if $K=\Delta$ on the maximal domain in $L_2(\mathbb{R}^n)$, then $D(K)=W_2^2(\mathbb{R}^n)$ and $D((-K)^\alpha)=W_2^{2\alpha}(\mathbb{R}^n)$ and the heat semigroup regularizes initial conditions.

Perturbation techniques

Verifying conditions of the Hille–Yosida theorem for a concrete problem is usually an impossible task. Then we consider

Problem P. Let (A, D(A)) be a generator of a C_0 semigroup on a Banach space X and (B, D(B)) be another
operator in X. Under what conditions does A + B, or an
extension K of A + B, generate a C_0 -semigroup on X?

Power of positivity and L_1 spaces

Recall that natural state spaces for fragmentation and coagulation problems are $X_1 = L_1(\mathbb{R}_+, xdx)$ and $X_{0,\alpha} = L_1(\mathbb{R}_+, (1+x^{\alpha})dx)$.

They are Banach lattices. In a Banach lattice X we can identify the cone of positive elements X_+ and define $Z_+ := Z \cap X_+$ for $Z \subset X$.

Definition 4

We say that the semigroup $(G(t))_{t\geq 0}$ on X is positive if for any $f\in X_+$ and t>0,

$$G(t)f \geq 0$$
.

From now on, X is an L_1 -space. We say that $(G(t))_{t\geq 0}$ is a substochastic semigroup if for any $t\geq 0$ and $f\geq 0$, $G(t)f\geq 0$ and $\|G(t)f\|\leq \|f\|$, and a stochastic semigroup if additionally $\|G(t)f\|=\|f\|$ for $f\in X_+$.

With regards to Problem P., the existence of a semigroup $(G_K(t))_{t\geq 0}$ associated with

$$f_t = Af + Bf$$

depends to large extent on whether we can prove

- a) $||BR(\lambda, A)|| < 1$, or only
- b) $||BR(\lambda, A)|| \le 1$.

In case b), we have Kato type theorem:

Theorem 5

Let $X = L_1(\Omega, \mu)$ and suppose that the operators A and B satisfy

- 1. (A, D(A)) generates a substochastic semigroup $(G_A(t))_{t\geq 0}$;
- 2. $D(B) \supset D(A)$ and $Bf \ge 0$ for $f \in D(A)_+$;
- 3. for all $f \in D(A)_+$ $\int\limits_{\Omega} (Af + Bf) d\mu \le 0. \tag{27}$

Then there is an extension (K, D(K)) of (A + B, D(A)) generating a positive C_0 -semigroup of contractions, say, $(G_K(t))_{t\geq 0}$.

In case a), we have the Desch-Miyadera type theorem,

Theorem 6 (W. Desch)

Let $(G_A(t))_{t\geq 0}$ be a positive C_0 -semigroup on some L^1 space X with generator A and let B be positive on $D(A)_+$. If $\|BR(\lambda,A)\|<1$ for large $\lambda>0$, then

$$K = A + B : D(A) \rightarrow X$$

is the generator of a positive C_0 -semigroup on X.

Moreover, if $(G_A(t))_{t\geq 0}$ is analytic, $(G_K(t))_{t\geq 0}$ is also analytic.

Back to the pathologies of the fragmentation problem

Recall

$$f_{t}(x,t) = \mathcal{A}f(x,t) + \mathcal{B}f(x,t)$$

$$= -a(x)f(x,t) + \int_{x}^{\infty} a(y)b(x,y)f(y,t)dy.$$
 (28)

We denote

$$F_{\mathsf{min}} = A + B$$
, on $D(F_{\mathsf{min}}) = D(A) = \{f, \mathsf{a}f \in L_1(\mathbb{R}_+, \mathsf{x} dx)\}$

and

$$F_{\mathsf{max}} = \mathcal{A} + \mathcal{B}$$
 on $D(F_{\mathsf{max}}) = \{f, \mathcal{A}f + \mathcal{B}f \in L_1(\mathbb{R}_+, x dx)\}.$

Since, using (8), we get

$$\int_{0}^{\infty} \left(-a(x)u(x) + \int_{0}^{\infty} a(y)b(x,y)u(y)dy \right) xdx = 0$$

for $0 \le f \in D(F_{\min}) = D(A)$, there is a generator, say F, of a substochastic fragmentation semigroup associated to (28). Hence, if the solutions are in $D(F_{min}) = D(A) = D(B)$, then

$$\partial_t \| u(t) \|_{X_1} = \int_0^\infty (Au(t) + Bu(t)) x dx$$
$$= \int_0^\infty Au(t) x dx + \int_0^\infty Bu(t) x dx = 0$$
(29)

so that $(G_K(t))_{t>0}$ is mass-conserving.

The conservativeness may be extended to the case, when the solutions stay in $D(\overline{F_{\min}})$, where $\overline{F_{\min}}$ is explicitly defined as

$$\overline{F_{\min}}f = \lim_{n \to \infty} (Af_n + Bf_n)$$

where $D(F_{\min}) \ni f_n \to f \in D(\overline{F_{\min}})$, whenever the limits exist.

Then it is easy to see that (29) holds for $f(t) \in D(\overline{F_{\min}})$

$$\int_{0}^{\infty} \overline{A + B} f(t) x dx = 0.$$
 (30)

But does $f(t) \in D(\overline{F_{\min}})$?

$F, F_{min}, \overline{F_{min}}, F_{max}$ and pathologies of the model.

The generator F always satisfies $F_{\min} \subset F \subset F_{\max}$. The place of F on this scale determines the well-posedness of the problem (28).

All following situations are possible

Each of these cases has its own specific interpretation in the model.

If $F \subsetneq F_{\text{max}}$, we don't have uniqueness: there are differentiable X_1 -valued solutions to emanating from zero and therefore they are not described by the semigroup:

'there is more to life, than meets the semigroup'.

If $\overline{F_{\min}} \subsetneq F$, then despite the fact that the equation is formally conservative, the solutions are not: the modelled quantity leaks out from the system and the mechanism of this leakage is not present in the model.

Typical dynamics in $L_1(\mathbb{R}_+, x dx)$

Let a(x) be such that both limits $\lim_{x\to\infty,0} a(x)$ (possibly infinite) exist and let $b(x,y)=(\nu+2)x^{\nu}/y^{\nu+1}$. Then,

$$F = F_{max} \quad \text{iff} \quad \frac{1}{xa(x)} \notin L_1([N,\infty)),$$
 (31)

$$F = \overline{F_{min}}$$
 iff $\frac{1}{xa(x)} \notin L_1([0, \delta]),$ (32)

for some $N, \delta \in (0, \infty)$.

Fragmentation in higher moment spaces.

Assume that

a is bounded at 0 &
$$\int_{0}^{y} b(x, y) dy = n_0(y) \le b_0(1 + y^l)$$
, (33)

where $l \in [0, \infty[$ and $b_0 \ge 1$. Recall the notation

$$X_{0,m} = L_1(\mathbb{R}_+, (1+x^m)dx).$$
 (34)

We note that, due to the continuous injection $X_{0,m} \hookrightarrow X_1$, $m \ge 1$, any solution in $X_{0,m}$ is also a solution in the basic space X_1 .

Further, define

$$n_m(y) := \int_0^y b(x,y) x^m \mathrm{d} x$$

for any $m \geq 0$ and $y \in \mathbb{R}_+$, and

$$N_0(y) := n_0(y) - 1 \ge 0,$$

$$N_m(y):=y^m-n_m(y)\geq 0,\quad m\geq 1,$$

with $N_1 = 0$.

Theorem 7

Let a, b satisfy (33) and for some $m_0 > 1$

$$\liminf_{y \to \infty} \frac{N_{m_0}(y)}{y^{m_0}} > 0.$$
(35)

Then

- ① (35) holds for all m > 1;
- ② F := A + B is the generator of a positive analytic semigroup $(G_F(t))_{t \ge 0}$, on $X_{0,m}$ for any $m > \max\{1, l\}$.

Example 8

One of the forms of b(x, y) most often used in applications is

$$b(x,y) = \frac{1}{y}h\left(\frac{x}{y}\right) \tag{36}$$

which is referred to as the homogeneous fragmentation kernel. In this case the distribution of the daughter particles does not depend directly on their relative sizes but on their ratio. In this case

$$n_m(y) = \frac{1}{y} \int_0^y h\left(\frac{x}{y}\right) x^m dx = y^m \int_0^1 h(z) z^m dz =: h_m y^m.$$

Example 9

Since

$$y = n_1(y) = \frac{1}{y} \int_0^y h\left(\frac{x}{y}\right) x dx = y \int_0^1 h(z) z dz = h_1 y$$

we have $h_1=1$ so that $h_m<1$ for any m>1 and

$$N_m(y) = y^m(1 - h_m)$$
. Hence, (35) holds.

On the other hand, fragmentation processes in which daughter particles tend to accumulate close both to 0 and to the parent's size may not satisfy (35).

Full fragmentation-coagulation problems

Recall that we deal with the equation

$$\partial_t f(x,t) = -a(x)f(x,t) + \int_x^\infty a(y)b(x,y)f(y,t)dy$$
$$-u(x,t)\int_0^\infty k(x,y)f(y,t)dy$$
$$+\frac{1}{2}\int_0^x k(x-y,y)f(x-y,t)u(y,t)dy. \tag{37}$$

Next, we denote by C the nonlinear part of (37) so that the initial value problem for (37) can be written as

$$\partial_t f = Ff + Cf, \qquad u(0) = \mathring{f}. \tag{38}$$

A brief on semilinear problems

Next we consider the semilinear abstract Cauchy problem

$$f_t = Kf + g(f), \tag{39a}$$

$$f(0) = \mathring{f},\tag{39b}$$

where K is the generator of $(G_K(t))_{t\geq 0}$ and g is a known function in X. We approach the problem using the integral formulation

$$f(t) = G_{\mathcal{K}}(t)\mathring{f} + \int_{0}^{t} G_{\mathcal{K}}(t-s)g(f(s))ds. \tag{40}$$

For this to work, g must be a Lipschitz function on X - no unbounded g is allowed.

It is possible to relax the restrictions on g, when $(G_K(t))_{t\geq 0}$ is an analytic semigroup. If we take $0\leq \alpha<1$ and $t\mapsto f(t)$ is $D((-K)^\alpha)$ -valued, then for $\mathring{f}\in D((-K)^\alpha)$ we can write

$$(-K)^{\alpha}f(t) = G_K(t)(-K)^{\alpha}\mathring{f}$$

$$+ \int_0^t (-K)^{\alpha}G_K(t-s)g((-K)^{-\alpha}(-K)^{\alpha}f(s))\mathrm{d}s,$$

where the integral is defined if $h(\cdot)=g((-K)^{-\alpha}\cdot)$ is bounded as a function from $D((-K)^{\alpha})$ to X. In other words, we repeat the Picard iteration process in X for $v(t)=(-K)^{\alpha}f(t)$; that is,

$$v(t) = G_{\mathcal{K}}(t)\mathring{v} + \int_{0}^{t} (-\mathcal{K})^{\alpha} G_{\mathcal{K}}(t-s)h(v(s))\mathrm{d}s,$$

where $\mathring{v}=(-K)^{\alpha}\mathring{u}$. For this h should be Lipschitz continuous in X; that is, it suffices that g be only Lipschitz continuous from $D((-K)^{\alpha})$ to X. Due to the integrable singularity that appears under the sign of the integral due to (26),

$$||t^{-\alpha}(-K)^{-\alpha}G_K(t)|| \leq M_{\alpha},$$

we obtain a Volterra equation with a weakly singular kernel.

Back to the fragmentation-coagulation equation

We assume that b satisfies (33), F = A + B generates an analytic semigroup, and the coagulation kernel k(x, y) satisfies

$$0 \le k(x,y) \le L((1+a(x))^{\alpha}(1+a(y))^{\alpha}, \tag{41}$$

for some L>0 and $0\leq \alpha<1$. This will suffice to show local in time solvability of (37), whereas to show that the solutions are global in time we need to strengthen (57) to

$$0 \le k(x,y) \le L((1+a(x))^{\alpha} + (1+a(y))^{\alpha}). \tag{42}$$

To formulate the main theorem we have to introduce a new class of spaces which, as we shall see later, is related to intermediate spaces which play the role of the domains of fractional powers of -F,

$$X_m^{(\alpha)}:=\left\{f\in X_{0,m};\ \int_0^\infty |f(x)|(\omega+a(x))^\alpha(1+x^m)\,dx<\infty\right\},$$

where ω is a sufficiently large constant. We assume that all assumptions that ensure analyticity of $(G_F(t))_{t\geq 0}$ are satisfied.

Then

Theorem 10

1. If k satisfies (57), then, for each $\mathring{f} \in X_{m,+}^{(\alpha)}$, there is $t_{max}(\mathring{f}) > 0$ such that the initial-value problem (38) has a unique nonnegative classical solution f in $X_m^{(\alpha)}$, that is,

$$f \in C\left([0, t_{max}(\mathring{f})), X_m^{(\alpha)}\right) \cap C^1\left((0, t_{max}(\mathring{f})), X_m^{(\alpha)}\right).$$

2. If k satisfies (42), then, for each $\mathring{f} \in X_{m,+}^{(\alpha)}$, the corresponding local nonnegative classical solution is global in time.

Example 11

Suppose we have $a(x) = x^j, j > 0$, and $k(x, y) = x^{\beta} + y^{\beta}$. Then we can write

$$k(x,y) = a(x)^{\beta/j} + a(y)^{\beta/j}$$

so that $\alpha=\beta/j$. The assumption for local solvability require $\alpha<1$; that is, $\beta< j$. The same condition is required for global solvability. On the other hand, if $k(x,y)=x^\beta y^\beta$, then the conditions of the local solvability remain the same, while from

$$2x^{\beta}y^{\beta} \le x^{2\beta} + y^{2\beta},$$

it follows that we require $\beta < j/2$.

Relation to weak solutions

Weak solutions to (37) are constructed as weak limits of solutions u_r to the problem with the coefficients a and k modified as follows

$$a_r(x) = \left\{ egin{array}{ll} a(x) & ext{for} & x \leq r \\ 0 & ext{for} & x > r, \end{array}
ight. \quad k_r(x,y) = \left\{ egin{array}{ll} k(x,y) & ext{for} & x + y \leq r \\ 0 & ext{for} & x + y > r. \end{array}
ight.$$

Theorem 12

Assume that the assumptions of Theorem 10 are satisfied and u is the solution to (38). If $(u_r)_{r>0}$ are approximate solutions defined above, then

$$\lim_{r \to \infty} u_r = u \tag{43}$$

in $C([0,T],X_m^{(\alpha)})$ for any $T < t_{max}(\mathring{f})$.

Back to the fragmentation-coagulation equation with growth

Let us recall that we are dealing with the problem

$$\partial_t f(x,t) = -\partial_x [r(x)f(x,t)] + Ff(x,t) + Cf(x,t),$$

$$f(x,0) = \mathring{f}(x),$$
 (44)

where we assume

$$0 \le a \in L_{\infty,loc}([0,\infty)); \tag{45}$$

$$1/r \in L_{1,loc}(\mathbb{R}_+) \text{ and } 0 < r(x) \le r_0 + r_1 x \le \tilde{r}(1+x),$$
 (46)

for some nonnegative constants r_0 , r_1 and \tilde{r} .

We distinguish two cases of behaviour of r(x) close to x = 0:

$$\int_{0^+} \frac{\mathrm{d}x}{r(x)} = +\infty \text{ or } \int_{0^+} \frac{\mathrm{d}x}{r(x)} < +\infty.$$
 (47)

In the latter, we need a boundary condition at x=0 and hence we define $T_0f:=-(rf)_x-af$, in the first case on

$$D(T_0) := \{ f \in X_{0,m} : (rf)_x, qf \in X_{0,m} \}, \tag{48}$$

and in the second case we use

$$D(T_0) := \{ f \in X_{0,m} : (rf)_x, qf \in X_{0,m}, r(x)f(x) \to 0 \text{ as } x \to 0 \}.$$
(49)

We consider the full linear part in the abstract form

$$f_t = T_0 f + B f, \ t > 0; \ f(0) = \mathring{f},$$
 (50)

where B is the restriction to $D(T_0)$ of

$$f \mapsto \int_{x}^{\infty} a(y)b(x,y)f(y)dy.$$

Then, under the same assumptions on b that ensured analyticity of the fragmentation semigroup, we have

Theorem 13

Then
$$(K, D(T_0)) = (T_0 + B, D(T_0))$$
 generates a positive C_0 -semigroup, $(G_K(t))_{t \geq 0}$, on $X_{0,m}$.

The proof is carried out by the Desch theorem, applicable since we deal with positive operators in L_1 spaces.

An application to spectral gap and AEG.

Theorem 14

Let the assumptions of the previous theorem be satisfied, and let r be continuous, satisfy (46) and 1/r be integrable close to 0^+ . Further, let the sublevel sets of a be thin at infinity in the sense that for any c>0

$$\int_{1}^{+\infty} 1_{\{x>0: \ a(x)< c\}} \frac{1}{r(y)} dy < +\infty \tag{51}$$

(e.g., let $\lim_{x\to +\infty} a(x)=+\infty$). Then $(G_K(t))_{t\geq 0}$ has AEG, that is,

Theorem 14

there is $\varepsilon > 0$ such that

$$\left\| e^{-\lambda t} G_{K}(t) \mathring{f} - (\mathbf{e}^{*} \cdot \mathring{f}) \mathbf{e} \right\| = O(e^{-\varepsilon t}), \tag{52}$$

where λ is the isolated algebraically simple dominant eigenvalue of K, and \mathbf{e} and \mathbf{e}^* are strictly positive eigenvectors of, respectively, the generator and its dual.

Application to problems with coagulation

For pure fragmentation and coagulation problems (with $r\equiv 0$), the linear part generates an analytic semigroup $(G_F(t))_{t\geq 0}$ which allows to deal with the integral equation

$$f(t) = G_F(t)\mathring{f} + \int_0^t G_F(t-s)Cf(s) ds, \ t \in \mathbb{R}_+.$$
 (53)

even when the kernel k of C is unbounded (but with growth controlled by a).

With $r \neq 0$, however, $(G_K(t))_{t \geq 0}$ is not analytic.

Moment regularization. We have the following result.

Theorem 15 (E. Bernard & P. Gabriel, 2020)

In addition to the conditions required for Theorem 13 to hold, assume that positive constants a_0 , γ_0 and x_0 exist such that

$$a(x) \ge a_0 x^{\gamma_0}, \quad \text{for all } x \ge x_0.$$
 (54)

Then, for any n, p and m satisfying $\max\{1, I\} < n < p < m$, there are constants C > 0 and $\theta > 0$ such that

$$\|G_{K}(t)\mathring{f}\|_{0,m} \le Ce^{\theta t} t^{\frac{n-m}{\gamma_0}} \|f\|_{0,p}, \text{ for all } f \in X_{0,p}.$$
 (55)

Full problem (44)

Here, the coagulation kernel is required to satisfy

$$k(x,y) \le k_0(1+x^{\alpha})(1+y^{\alpha}),$$
 (56)

for some $0 < \alpha < \gamma_0$.

Assume that the generation assumptions of this section hold, k satisfy (56) and, in addition, $m > \alpha + \max\{1, l\}$.

Theorem 16

Then, for each $\mathring{f} \in X_{0,m,+}$, the problem (44) has a unique nonnegative mild solution $f \in C([0,t_{\max}),X_{0,m})$ defined on its maximal interval of existence $[0,t_{\max}(\mathring{f}))$. If $t_{\max}(\mathring{f}) < \infty$, then $\|f(t)\|_{0,m}$ is unbounded as $t \to t_{\max}(\mathring{f})^-$.

In the next theorem we address the issue of differentiability of the mild solution and it being a classical solution. The result is similar to that for analytic semigroups in that the mild solution in a smaller space (here $X_{0,m}$) is a classical solution in a bigger space (here $X_{0,p}$). Denote by $D_p(K)$ the domain of K in $X_{0,p}$.

Theorem 17

Assume that $\mathring{f} \in X_{0,m} \cap D_p(K)$, where $p = m - \alpha$. Then the mild solution f constructed in Theorem 16, defined on its maximal interval of existence $[0, t_{\text{max}})$, satisfies $f \in C([0, t_{\text{max}}), X_{0,m}) \cap C^1((0, t_{\text{max}}), X_{0,m}) \cap C((0, t_{\text{max}}), D_p(K))$ and is a classical solution to (44) in $X_{0,p}$.

Global solvability. For this, we assume

$$k(x,y) \le k_0(1+x^\alpha+y^\alpha), \tag{57}$$

 $0 < \alpha < \gamma_0$.

Theorem 18

If for $x \ge 0$ either

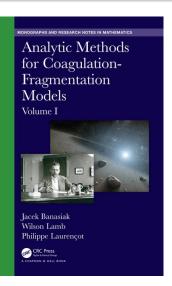
a) there are constants m_0 and m_1 such that

$$(n_0(x)-1)a(x) \leq m_0 + m_1 x,$$

or

b)
$$r(x) \leq \tilde{r}x$$
,

then the solutions of Theorem 16 are global in time.



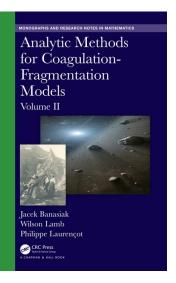


Figure: Shameless self-promotion

